

# Introduction to easyC<sup>®</sup> & Cortex<sup>™</sup>



# Cortex™ Microcontroller



# Cortex™ Joystick



# VEXNet™ USB Keys and Tether Cable

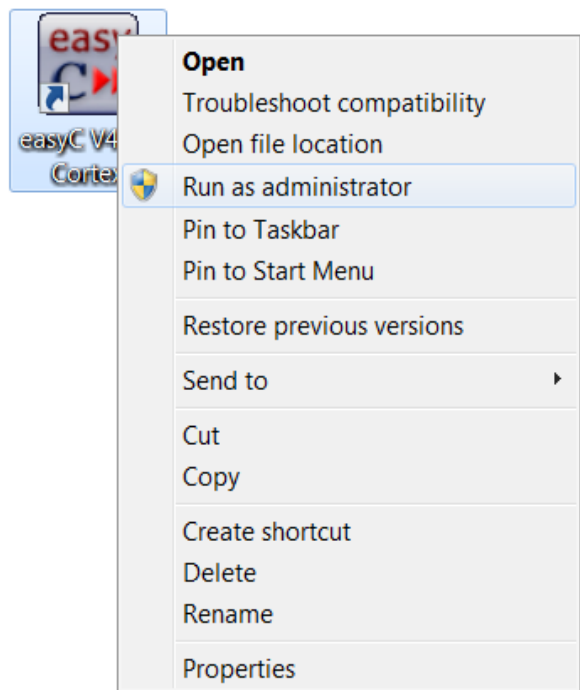


# easyC® V4 Programming CD

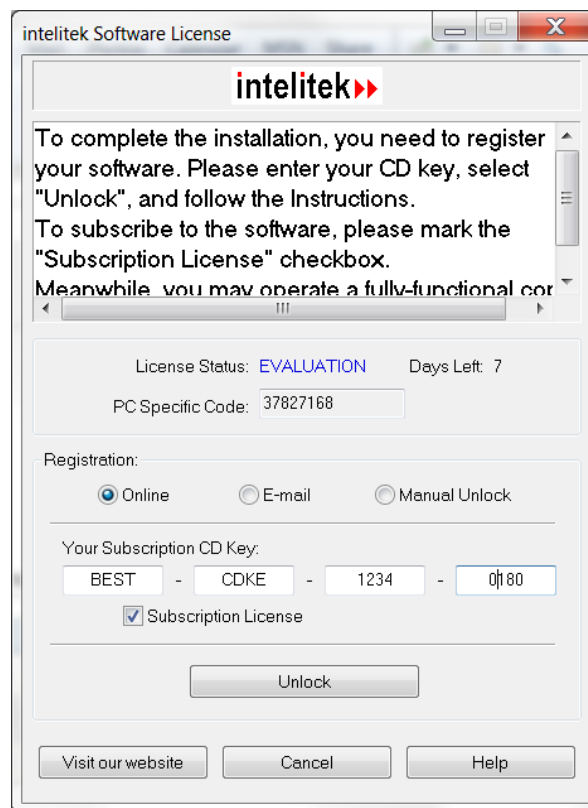


# Unlocking easyC®

Right-Click the easyC Icon, Click  
“Run as Administrator”

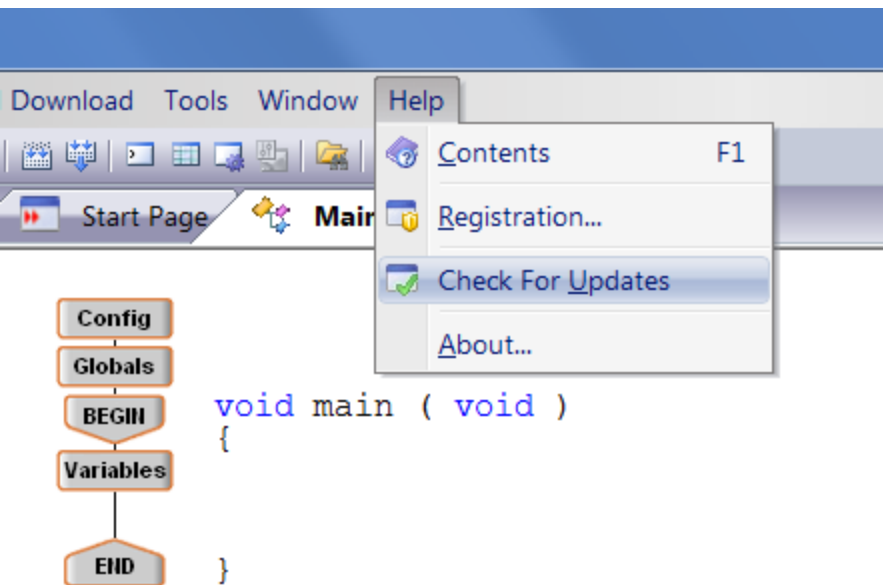


Type in you CD-Key and  
Click Unlock



# Updating easyC®

Go to Help -> Check For Updates, if the download site says to update download the latest version.



## Download easyC v4 - 4.0.0.1

You are currently running version **4.0.0.0** of easyC v4, this is **not** the current version. Intelitek recommends you download version 4.0.0.1 of easyC Pro to experience the full benefit of all easyC has to offer.

New features include:

- *Release Version*
- *Requires Mastercode Update*
- *File extensions changed to .ECPX*
- *UI Improvements*
- *Math Functions*
- *Improved Direct Download*
- *Changed Program Structure*
- *XP/Vista/7, 256MB RAM, 200MB HDD, 1024x768 Display*

# Updating Cortex™ Controller and Joystick

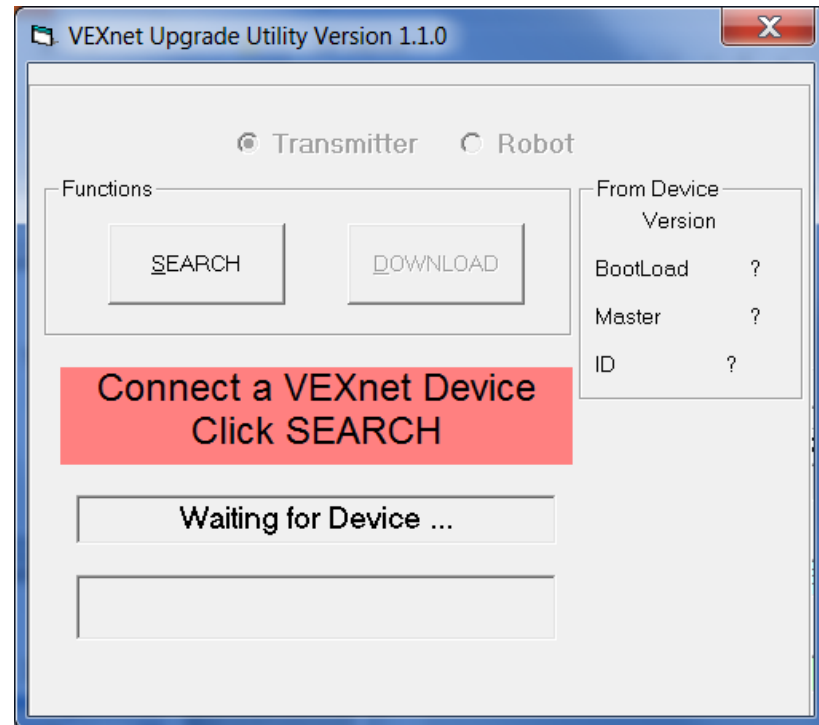
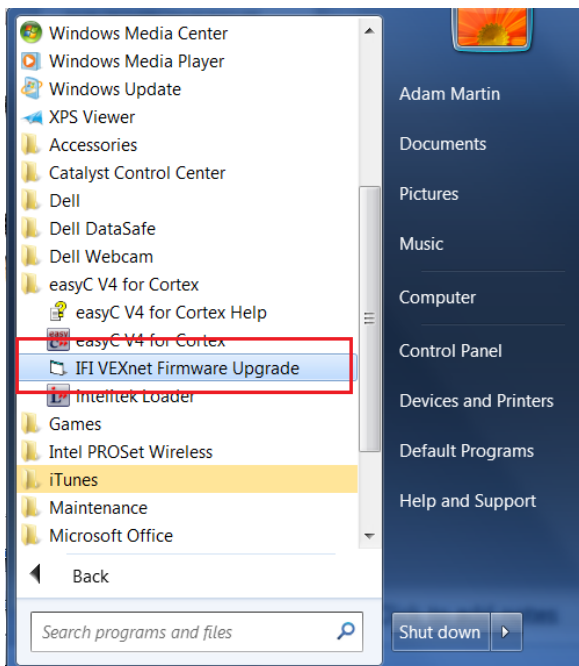
Remove the VEXNet™ key from the microcontroller and using the USB A-A cable connect the microcontroller to the computer. The LEDs should start flashing.





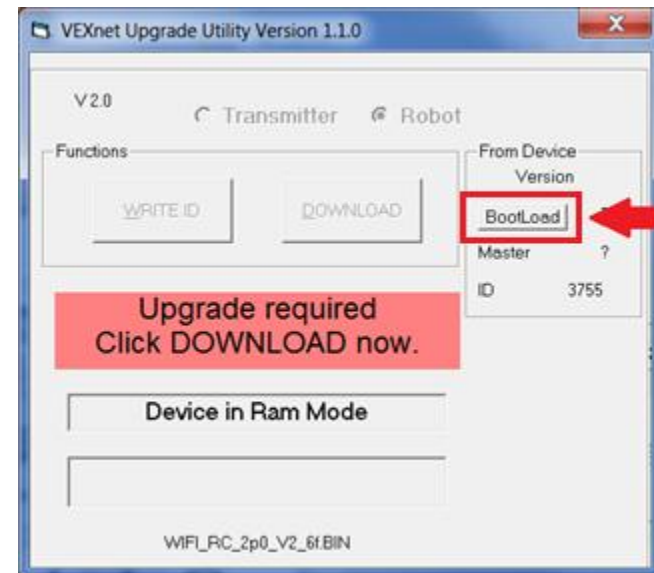
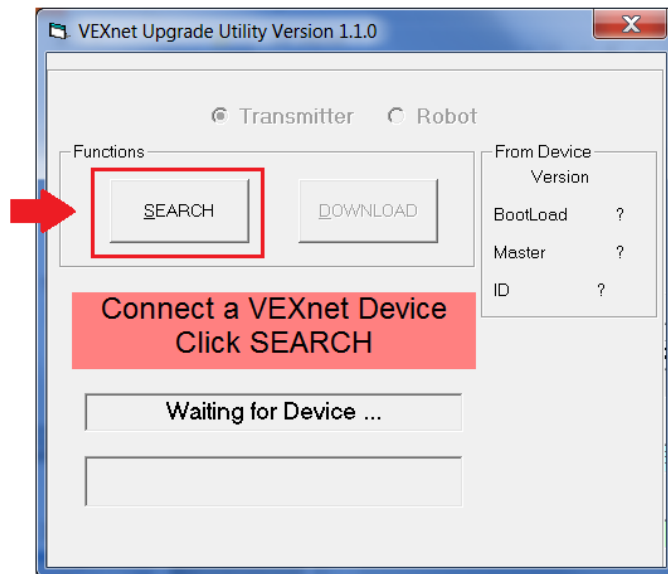
# Updating Cortex™ Controller and Joystick

Goto -> Start -> All Programs -> easyC v4 For Cortex -> IFI VEXNet Firmware Utility



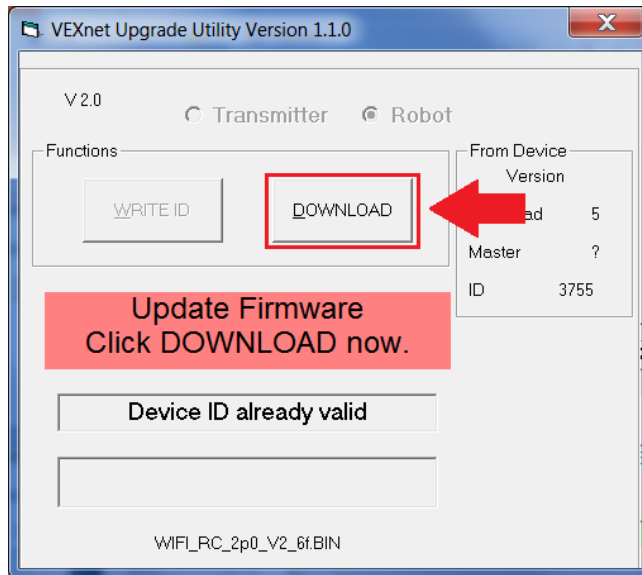
# Updating Cortex™ Controller and Joystick

Select “SEARCH” if the response is (Upgrade required) then “BOOTLOAD” and YES

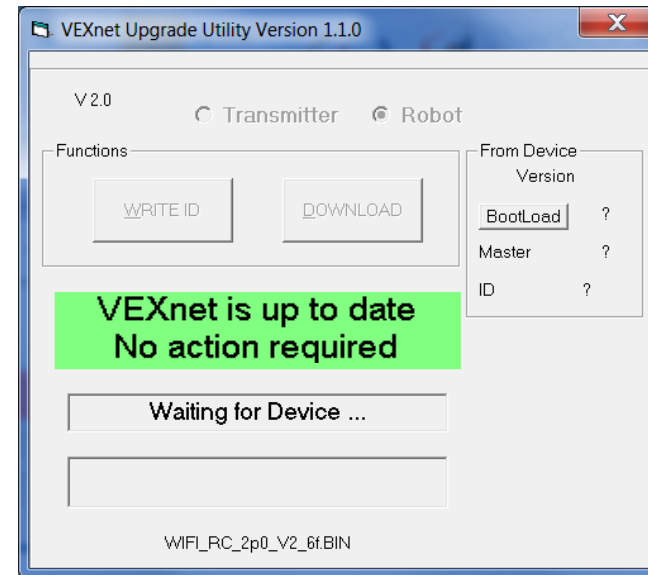


# Updating Cortex™ Controller and Joystick

Then click “DOWNLOAD”



Afterward you should see



# Updating Cortex™ Controller and Joystick

Now repeat the “SEARCH” -> “BootLoad” -> “DOWNLOAD” Process with the Joystick.

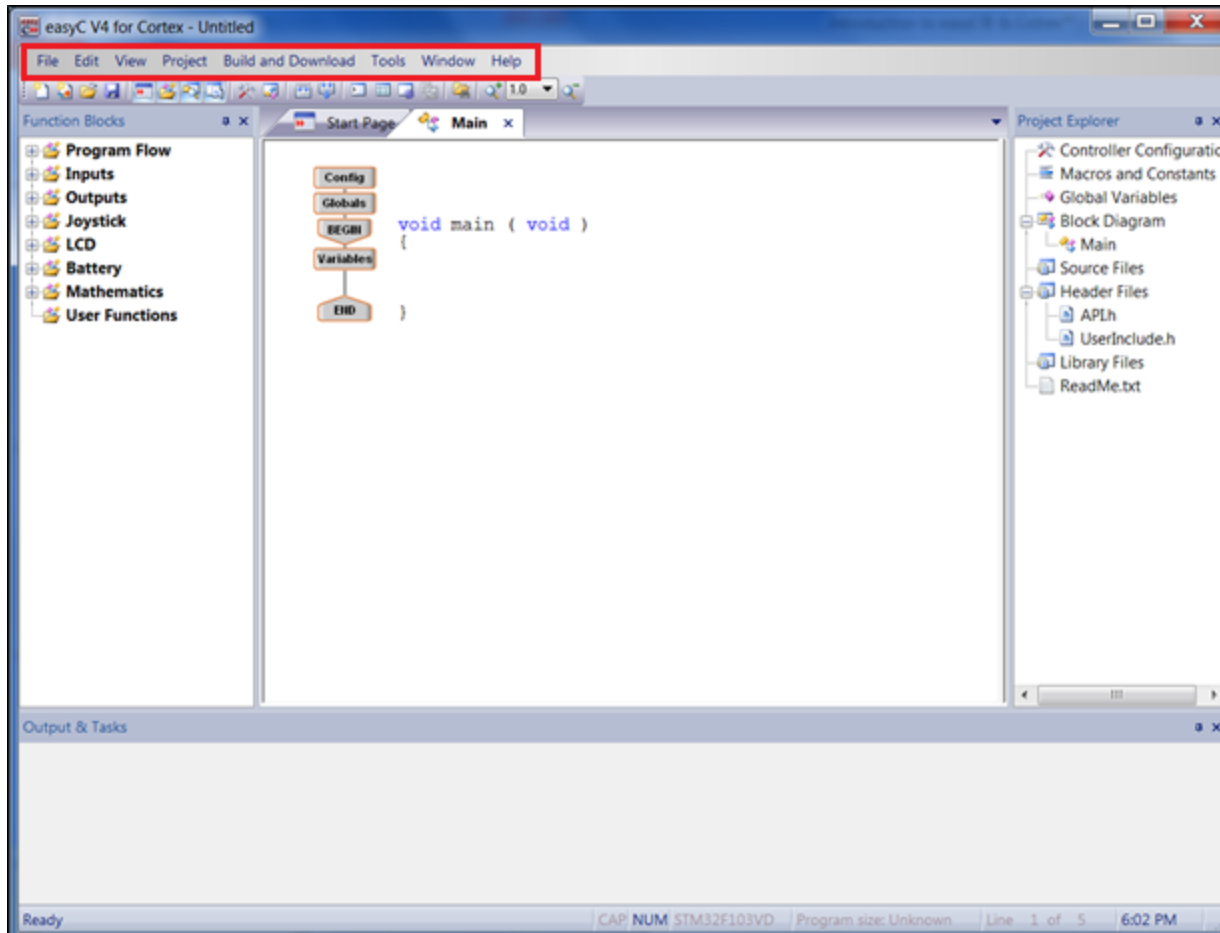


# Tethering Cortex™ Controller and Joystick

After updating the firmware on the joystick and microcontroller both devices must be paired together. Connect the two devices together and then turn on the joystick or microcontroller. Wait until the VEXNet™ LED turns solid green.



# easyC User Interface



## Menu Usage:

### File Menu

*New Project, Open, Close, Print*

### Edit Menu

*Undo, Edit, Copy, Paste, Find*

### Project Menu

*Project Type, Add Function, Import Function, Library Import*

### Build and Download Menu

*Compile, Build and Download, Reload Default IFI Code*

### Tools

*Terminal Window, Download Window, On-Line Window*

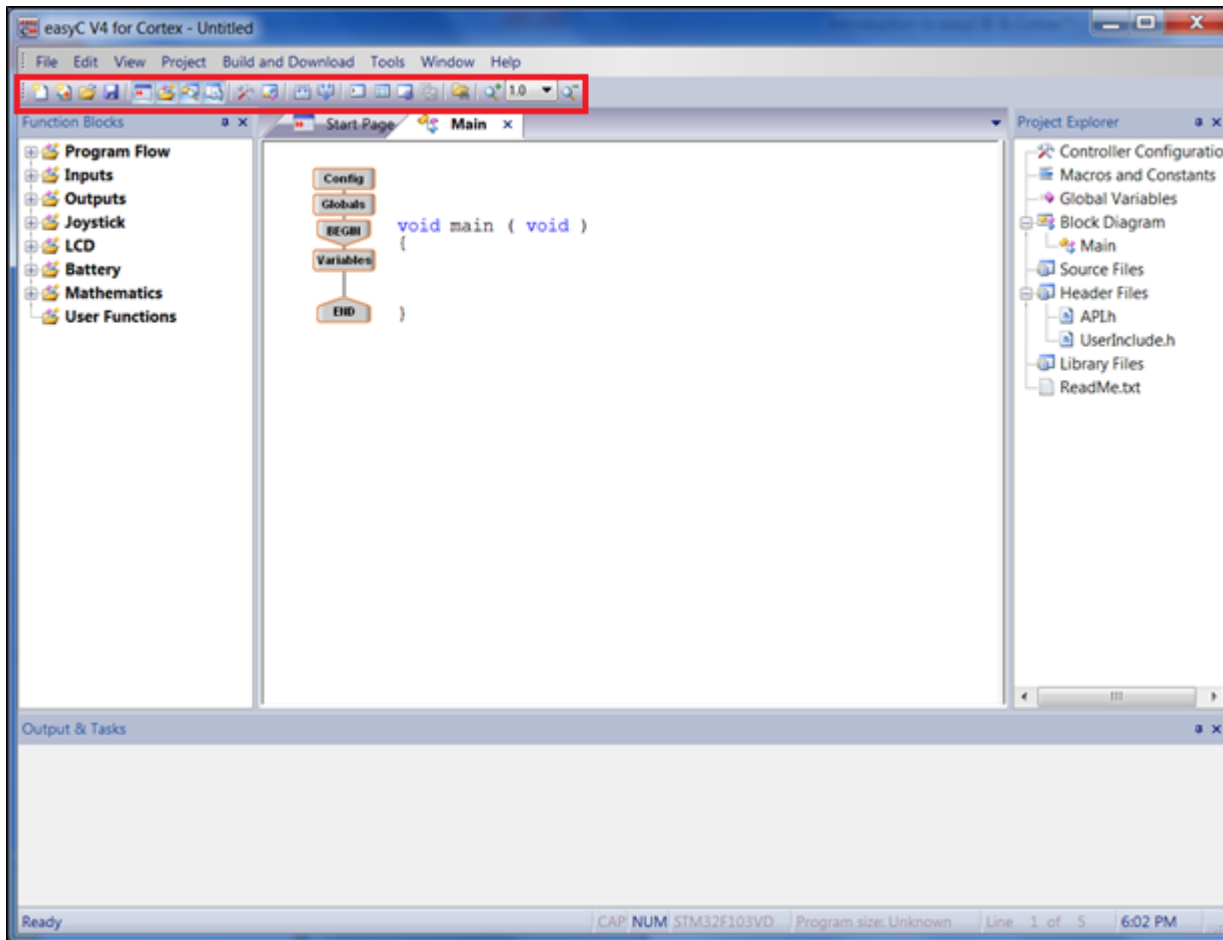
### Window

*Block Layout, Block & C Layout*











### Help Menu

*Contents, Registration, Updates*

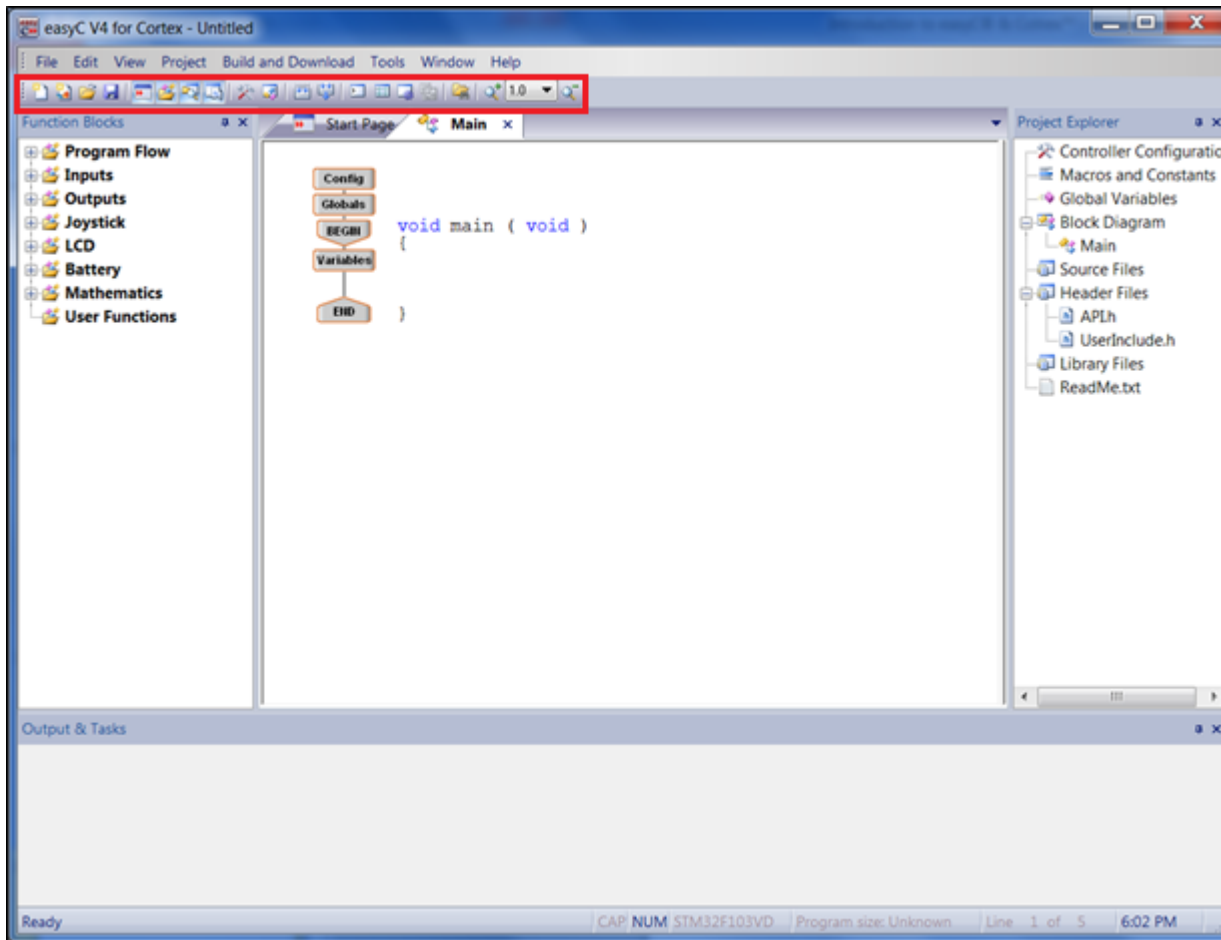
# easyC User Interface



## Icons


-  **New Project**
-  **New Competition Project**
-  **Open**
-  **Save**
-  **Start Page Enable**
-  **Function Blocks Enable**
-  **Project Explorer Enable**
-  **Output Panel Enable**
-  **Controller Configuration**
-  **Global Variables**

# easyC User Interface



## Icons

 **Compile**

 **Compile and Download**

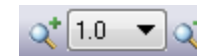
 **Terminal Window**

 **Graphic Display**

 **On-line Window**

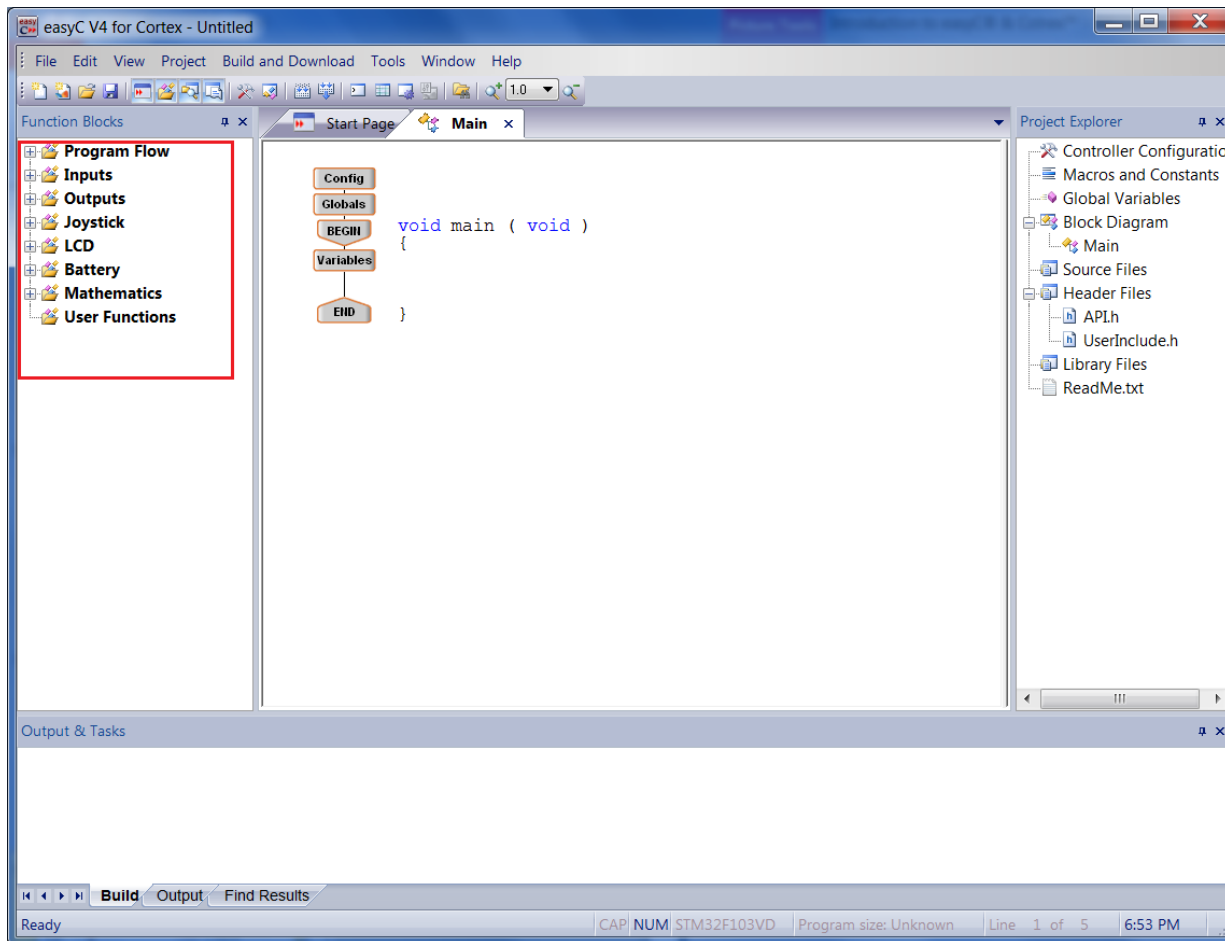
 **Find**

## Zoom





# easyC User Interface



## Function Blocks

### Program Flow

*Wait, If, Else, While, Timer, Assignment*

### Inputs

*Limit Switch, Digital Input, Analog Input, Potentiometer*

### Outputs

*Motor / Servo Module, Digital Output*

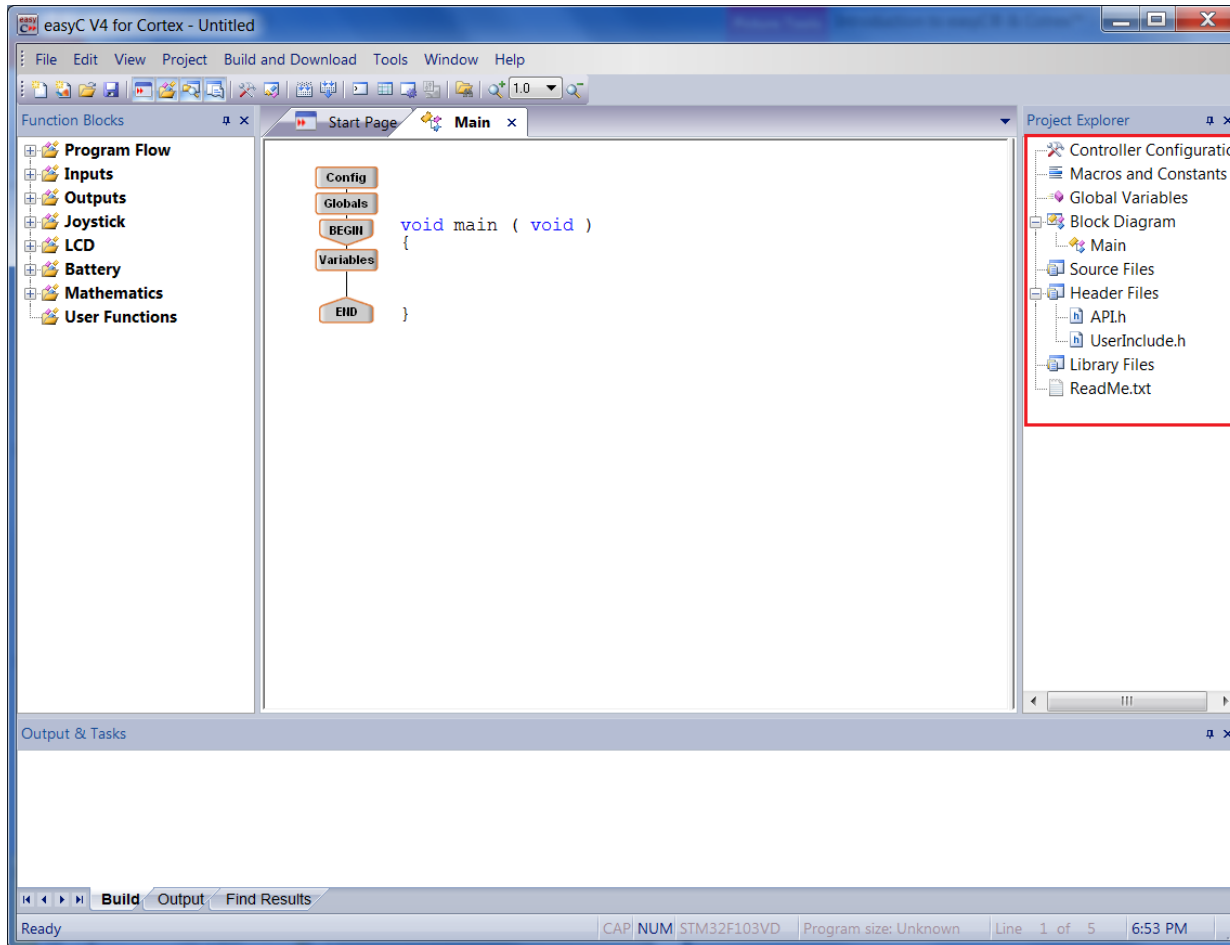
### Joystick

*Tank (2 Stick) , Arcade (Single Stick), Motor to Joystick, Motor to Digital (Button), Get Digital, Get Joystick*

### Mathematics

*SIN, COS, TAN, Power, Random*

# easyC User Interface



## Project Explorer

### Controller Configuration

*Change Inputs and Output, Label Ports*

### Macros and Constants

*Create Definitions (aka C #define)*

### Global Variables

*Variable with Global Program Scope*

### Block Diagram

*Select Between Functions*

### Source & Header Files

*Create or Import .c and .h files, Write C-Code Freehand*

### Library Files

*Import a easyC® library*


# easyC On-Line Window

On-Line Control (Enabled)

Disable    Reset All

Main Battery Voltage: 0.0    Backup Battery Voltage: 0.0

Motors:



#	Value	Set Group	Invert Direction
#1:	0	None	N/A
#2:	0	None	N/A
#3:	0	None	N/A
#4:	0	None	N/A
#5:	0	None	N/A
#6:	0	None	N/A
#7:	0	None	N/A
#8:	0	None	N/A
#9:	0	None	N/A
#10:	0	None	N/A

Digital I/O:

#1: 1	#5: 1	#9: <input type="checkbox"/>
#2: 1	#6: 1	#10: <input type="checkbox"/>
#3: 1	#7: 1	#11: <input type="checkbox"/>
#4: 1	#8: 1	#12: <input type="checkbox"/>

Analog Inputs:

#1: 64	#5: 63
#2: 63	#6: 64
#3: 64	#7: 63
#4: 65	#8: 64

Close    Help

Descriptions:    Show Defined    Save

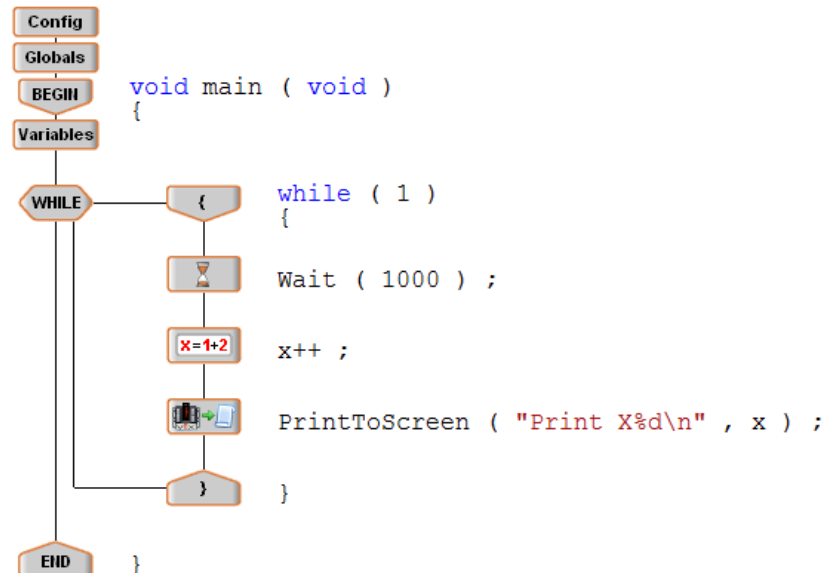
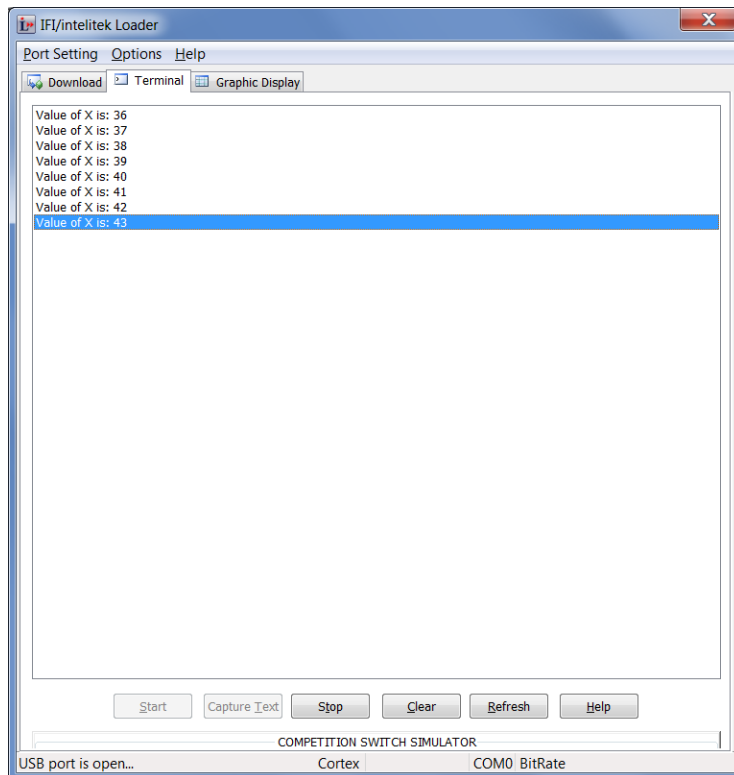
#	Description
<b>ANALOG INPUTS</b>	
1	
2	
3	
4	
5	
6	
7	
8	
<b>DIGITAL IN/OUT</b>	
1	
2	
3	
4	
5	
6	
7	
8	
9	
10	
11	
12	
<b>MOTORS</b>	
1	
2	
3	
4	
5	
6	
7	
8	
9	
10	

The easyC® On-Line Window allows the user to see and control motors and sensors attached to the robot in real time. This can be enabled at any time.

Note: The On-Line Window requires a program, even blank be downloaded after updating the master firmware.

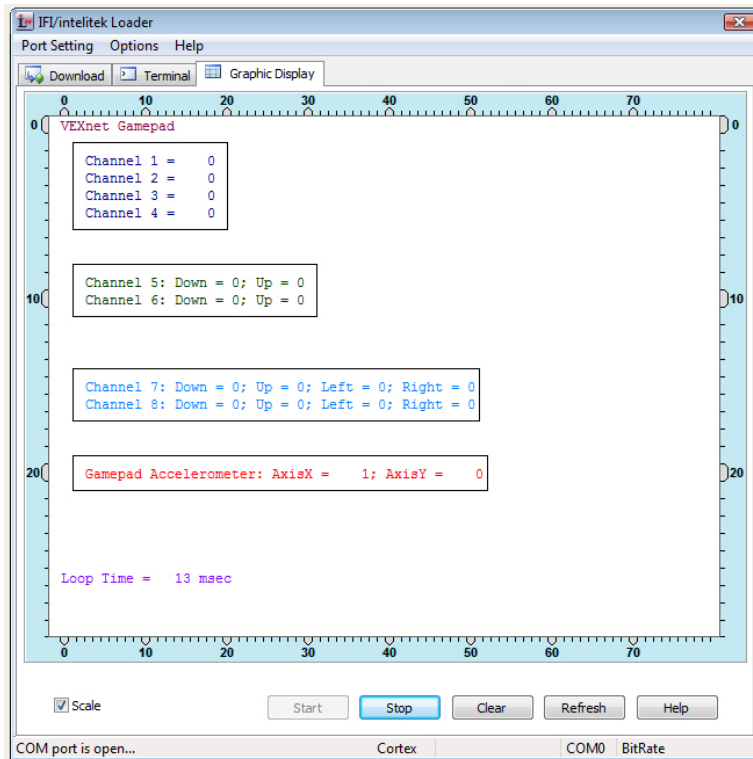
# easyC Terminal Window

The easyC allows users to see output from PrintToScreen calls form within their program while the program is running on the Microcontroller.



# easyC Terminal Window

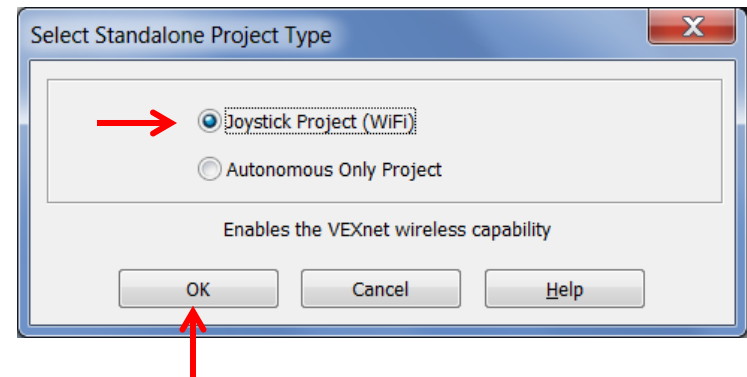
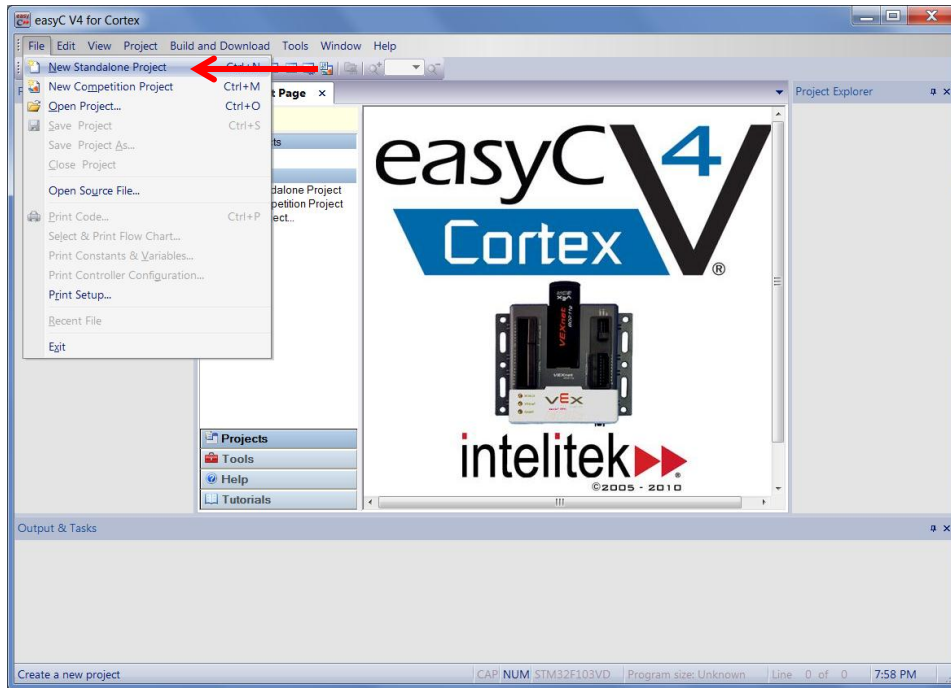
*The easyC allows users to see output from GraphicDisplay calls from within their program while the program is running on the Microcontroller. The Graphic Display is a more advanced type of feedback that allows values to be placed on grid instead of scrolling.*



*See Samples → “Graphic Display Joystick Test” for code.*

# Creating a New Program

1. Goto File -> New Standalone Project
2. Select Joystick Project (Wifi)
3. Click OK



# Simple Tank (2-Stick) Drive Example

*This simple program would drive a robot with motors connected to motor ports 2(left) and 3(right). Using joystick channels 2(right stick) and 3(left stick)*

**Tank - 2 motor** [X]

Transmitter:  
Joystick #: 1 (Value Range: 1..2)

Transmitter Channel:  
Left Channel: 3 (Value Range: 1..4)  
Right Channel: 2 (Value Range: 1..4)

Motor Number (Value Range: 1..10) and Invert Direction (Value Range: 0 - default, 1 - invert):

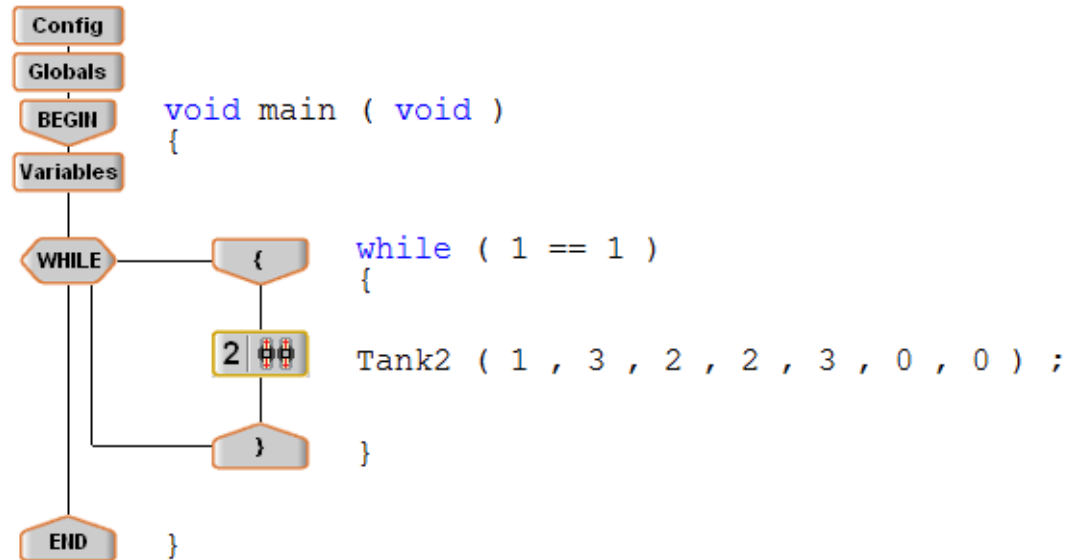
Left Motor 2	Right Motor 3
Invert Direction 0	Invert Direction 0

Code:  
Tank2 ( 1 , 3 , 2 , 2 , 3 , 0 , 0 );

Comment:

F6 - Globals and Constants    Ctrl + F6 - Local Variables

OK    Cancel    Help



# Simple Arcade ( 1-Stick ) Drive Example

*This simple program would drive a robot with motors connected to motor ports 2(left) and 3(right). Using joystick channels 2(left stick vertical) and 1(right stick horizontal)*

